

FRENIC4400VM5/FM5

DC-link 3-level Inverter with Vector and V/f Control



Fuji Electric Systems Co., Ltd.

High-accuracy and High-performance IGBT 3-level PWM Inverter

3-level PWM inverter

The adoption of 3-level PWM control enables an output voltage of 800V AC, hence a single unit can have a rated capacity of 1200kVA. Furthermore, the influence exerted over the motor/machine side can be reduced, as a 3-level inverter is capable of reducing the output harmonics and torque pulsation.

Output voltage waveform of 3-level inverter



IGBT utilized

This inverter has achieved a quick response, low-loss and simplification of the inverter control circuit due to the use of an IGBT (insulated-gate bipolar transistor).

Reduction of harmonic current on power supply side

The adoption of a diode converter of 12-phase rectification method permits reduction of the harmonic current on the power supply side. (Adoption of PWM converter (power supply harmonics = 0) is also feasible.)

Touch panel equipped with a liquid crystal display (*) (LCD)

Setting, running, monitoring and maintenance functions are all adjustable from the touch panel, equipped with a LCD on the unit front.

The LCD displays various data as well as key operational guidance on the bottom, thus facilitating operation.

(*): Available in both Japanese and English (switchable)





Enhanced support tools (option)

TUUObdizmu

Analog output for chart, PC loader, web-based remote monitoring, a high speed data acquisition system and other support tools are enhanced.

Connectable to different transmission lines (option)

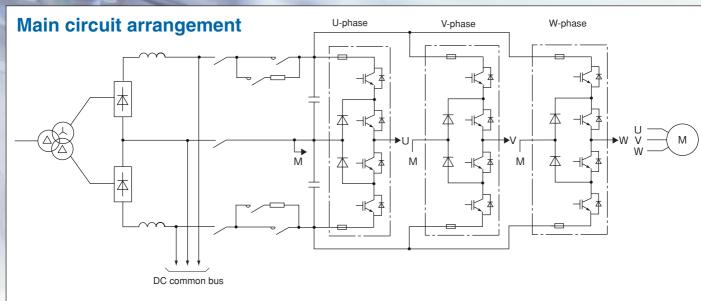
Connectable with a PLC or other high order controller at high speed and with limited wiring. In addition to Fuji's original D-line, T-link and SX bus, the PROFIBUS-DP, which is a typical open bus, is usable.

Wide choice of plant control functions

Based on previous operational experiences in different plants to date, various control functions useful for plant control are provided.

Highly-effective plant operation

The DC-link system allows power operational and regenerative energy to be transmitted and received via a DC common bus for highly efficient plant operation.



Specifications VM5/FM5

■ Common specifications

(*): Option

| Main circ Output vo Overload Control p Control function | capabi ower su Start/ stop | ility | Voltage-type IGBT sine wave PWM inverter 3-phase, 800V AC 150% for 1min 3-phase, 200/220V - 15 to +10% Touch panel, Loader (*) Contact input, Analog input (±10V) D-line/T-link (*), SX bus (*) PROFIBUS-DP (*) | | |
|--|--|--|--|--|--|
| Overload Control p | capabi ower su Start/ stop | Lippiy Key operation External signal Transmission link operation | 150% for 1min 3-phase, 200/220V - 15 to +10% Touch panel, Loader (*) Contact input, Analog input (±10V) D-line/T-link (*), SX bus (*) PROFIBUS-DP (*) | | |
| Control p | Start/ stop | Lippiy Key operation External signal Transmission link operation | 3-phase, 200/220V - 15 to +10% Touch panel, Loader (*) Contact input, Analog input (±10V) D-line/T-link (*), SX bus (*) PROFIBUS-DP (*) | | |
| Control | Start/ stop | Key operation External signal Transmission link operation | Touch panel, Loader (*) Contact input, Analog input (±10V) D-line/T-link (*), SX bus (*) PROFIBUS-DP (*) | | |
| | Stop | External signal Transmission link operation | Contact input, Analog input (±10V) D-line/T-link (*), SX bus (*) PROFIBUS-DP (*) | | |
| function | Contac | Transmission link operation | D-line/T-link (*), SX bus (*) PROFIBUS-DP (*) | | |
| | | link operation | D-line/T-link (*), SX bus (*) PROFIBUS-DP (*) | | |
| | | ct input | | | |
| | Speed | | Built-in 12 points + 4 points (*) (2 points selectable×1, ×2) | | |
| | | I setting | Various transmission links, External signals, Touch panel, Loader (*) key operation | | |
| | Opera signal | tion status | Relay output (built-in 9 points + 8 points (*)) 3 points selectable (Y1, Y2, Y3) Analog output (built-in 4 points + externally mounted 4 points (*) + built-in 2 points (*)) | | |
| | Rotatir pickup | ng motor | The rotating motor is picked up in inverter operation (SY0). | | |
| | Restar mome failure | ntary power | Inverter is restarted without stopping the motor. | | |
| | Touch panel | | Each constant setting, Startup conditions, Control data digital display, Fault cause display Fault point data display | | |
| | Loader (*) | | Setting item, Startup conditions, Control data digital display, Fault cause display, Fault trace data display (*1) | | |
| | Analog output | | Analog output of arbitrary control data | | |
| | Charge lamp | | Comes on when residual voltage (25V DC or larger) is in the main circuit. | | |
| Protection | Protection level | | Classified into the following 4 levels. Major fault: Trips instantly. Medium fault: Quickly decelerates and trips to stop after the set time has elapsed. Minor fault 1: Cannot be restarted once it is stopped. Minor fault 2: Display only | | |
| | Overvo | oltage | Actuated when the DC main circuit voltage exceeds 1580V DC | | |
| | Under | voltage | On detecting undervoltage of DC intermediate voltage, inverter stops. | | |
| | Overh | | Protects the inverter by detecting the temperature of the heat sink inside the inverter. | | |
| | Short- | | Detected by "overcurrent." | | |
| | Overci | | Actuated when the output current peak value exceeds the overcurrent level (fixed). | | |
| | Groun | | By the operation of the converter side ground fault detection relay, inverter stops. | | |
| | Motor | (~2) | Protected by electronic thermal function and temperature detection. "Overload", "Motor overheat", "Startup congestion", "Overspeed" | | |
| Environ- | Installa locatio | n | Indoors, Free from corrosive gas, inflammable gas, dust, or explosive gas | | |
| ment | Ambie | nt temp. | 0 to +40℃ | | |
| | | | | | |
| | Ambie | nt humidity | 20 to 90% RH (no condensation) | | |
| | Ambie Coolin | g method | Forced air-cooled system | | |
| | Ambie Coolin Altitud | g method e | Forced air-cooled system Up to 1000m | | |
| | Ambie Coolin | g method e | Forced air-cooled system Up to 1000m 4.9m/s² or lower (at 10 to 50Hz) | | |
| | Ambie Coolin Altitud Vibrati Storage | g method e on (ambient temp.) | Forced air-cooled system Up to 1000m | | |

Note: (*1) Stores and displays control data of 225 points for the past two 1ms sampling. (*2) Only VM5 has the function of "motor overheat" and "overspeed" protection.

■ Individual specifications

(**): To be developed

| (). 10 be | | | | | |
|----------------------|------------------|---------------------------------------|---|--|--|
| Ту | | | FRENIC4400VM5 | | |
| Motor control system | | | Vector control | | |
| tion | Spee | d control | ASR fixed cycle 1ms | | |
| Function | ro | Maximum speed | 100Hz on inverter output frequency basis | | |
| | ont | Control range | 1:1000 | | |
| | or c | Control response | 25Hz (mechanical systems not included) | | |
| | Vector control | Speed control accuracy | ±0.01% of the maximum speed | | |
| | > | PG frequency | 100kHz or lower | | |
| | | Torque accuracy | ±5% of the rated torque | | |
| | Settin | g resolution | ±0.005% of the max. speed (20000d/100%) | | |
| | Accel time | eration/deceleration | 0 to 550.00s Linear (break point) acceleration/deceleration Acceleration/deceleration settable by transmission 2 types of deceleration for emergency stop | | |
| | ction | Multiplex winding motor driving | Up to 24 windings (8 multiplexing) without the output reactor | | |
| | Control function | Start/stop operation selection | The timing for releasing the brake or starting ASR can be controlled by 3 different signals (SY1, 2 and 3 by transmission) | | |
| | Co | Droop control | Torque drooping characteristics according to the speed. A fixed drooping type or speed command proportional type. | | |
| | | Torque control | Torque limit (2 types of transmission) Torque compensation (Transmission 2 types + analog input 1 point) Mechanical loss torque is compensated by polygonal approximation with set value (forward/reverse: 14 points) | | |
| | | Torque bias | Analog torque setting, Transmission torque setting (2 lines), Mechanical loss pattern, etc. | | |
| | | Observer | Load disturbance observer Vibration suppression observer | | |
| | | Acceleration/ deceleration forcing | Upon calculating the acceleration/deceleration torque based on the moment of inertia J and acceleration | | |
| | | Backlash correction | Corrects backlash during mechanical drive by several motors | | |
| | | Higher setting | Sets the speed higher than normal to cope with load impact | | |
| | | ω2 lock | Applies an electromagnetic brake during excitation to prevent the motor from needless rotation | | |
| | | di/dt limitation | Limits the gradient of the torque current command | | |
| | | Special braking | Stops the motor without regeneration (**) | | |
| | | | | | |

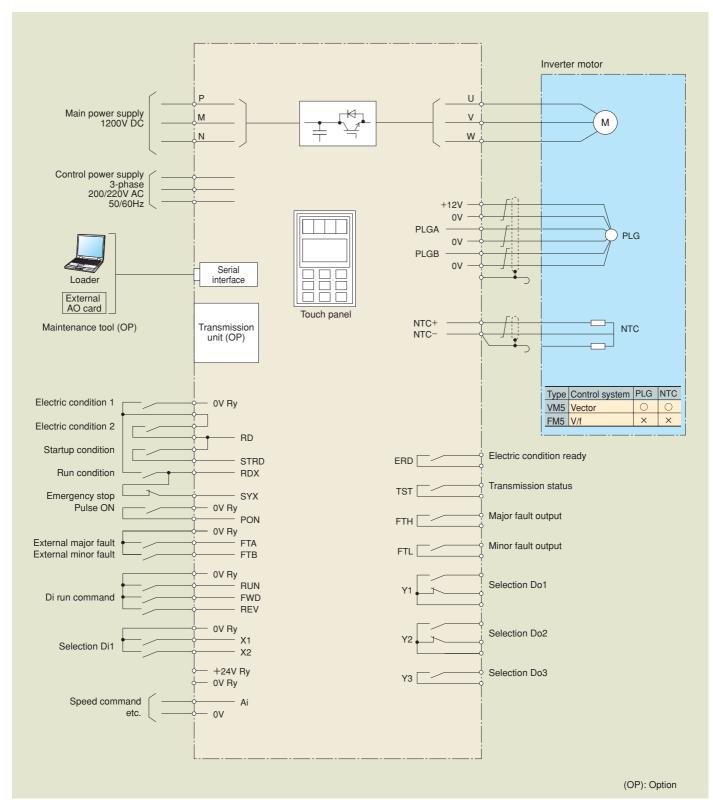
| Ту | ре | FRENIC4400FM5 | |
|----------|---------------------------------------|---|--|
| Mo | otor control system | V/f controlled AVR | |
| 5 | Output frequency | 2.5 to 100Hz | |
| Function | Frequency control range | 1:80 | |
| F. | Frequency control accuracy | ±0.01% of the maximum frequency | |
| | Field control range | 1:4 | |
| | Restart after momentary power failure | Inverter is restarted without stopping the motor. | |

Transmission options

| Card name | Use |
|-------------|--|
| DSM card | Connects the inverter with the host PLC via D-line, T-link |
| SX bus card | Connects the inverter with the host PLC via SX bus |
| PSB card | Connects the inverter with the host PLC via PROFIBUS-DP |

Standard interface

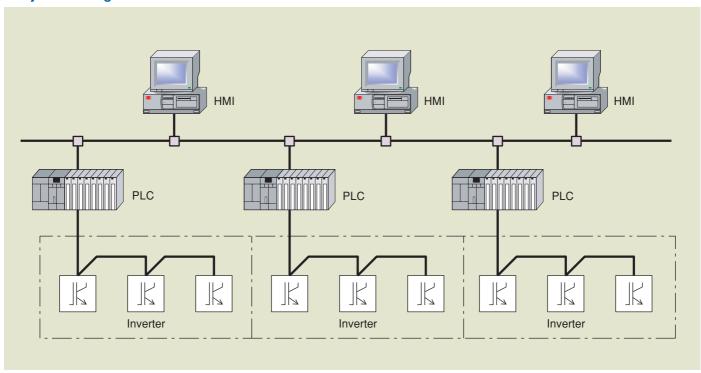
VM5/FM5



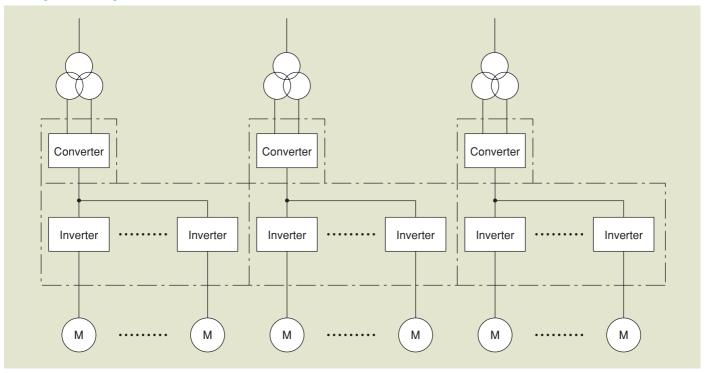
Example of system configuration and single-line diagram

VM5/FM5

■ System configuration



■ Single-line diagram



Data setting and monitoring (dedicated touch panel)

VM5/FM5

The touch panel equipped with a LCD displays a lot of information, and facilitates the functions of data setting, running operation and monitoring.

On the bottom of the LCD, key operational guidance appears, allowing you to perform almost all operations without referring to the instruction manual.

Up and down keys

Used for changing the Data Indication Nos. and the data setting values.

Program key

Reverts to the monitor screen (default) from any screen.

Shift key (digit shift)

Used to move the cursor from one digit to another in order to change data.

Reset key

When normal:

Assigned to "return" and "cancel" functions.

Returns to the previous layer.

At tripping:

Releases the stop status due to tripping.

Function/data selection key

Assigned to "enter" and "OK" functions.



Example of actual screen display

The monitor screen (default screen after turning on power) continually displays all of the current running statuses: speed command, detection, output current, output voltage and key operational guidance.

LED monitor (4 digits)

Displays the number of revolutions (changeable).

Any of 8 different data indicated on the LCD on the monitor screen can be selected arbitrarily.

At tripping:

"Err" blinks automatically, alerting you to the trip.

LCD monitor

Displays various information, including operational, set and fault data over a maximum of 5 lines \times 13 characters.

Operational guidance appears on the bottom.

On tripping, the trip data automatically appears.

Normal, reverse and stop keys

The operation can be started or stopped on the touch panel.

Use of touch panel (the No. of items is for VM5)

| Menu | Description | No. of items |
|---------|--|----------------------------|
| Initial | Monitor screen: Current, voltage and frequency display | Selected out of 2 pictures |
| M01 | Parameter setting reference and change | About 200 |
| M02 | Di/Do bit on/off status reference | 7 pictures |
| M03 | Ai/Ao voltage reference | 2 pictures |
| M04 | Inverter internal data display | About 90 |
| M05 | Transmission, sent/received data reference | About 60 |
| M06 | Inverter start, stop operation | 1 picture |
| M07 | Inverter startup condition on/off reference | 2 pictures |
| M08 | Latest fault code (simultaneous occurrence) reference | Up to 20 |
| M09 | Error history reference | Latest 40 |
| M10 | Inverter inside data reference on trip | About 20 |
| M11 | Present time setting, operating time reference, parameter setting control, liquid crystal concentration adjustment, etc. | About 10 pictures |

Introduction of some functions

●M09: Error history

Displays a chronological record of the past 40 faults with the causes and the time and date of occurrence, thereby allowing you to trace back errors.

•M10: Trip data display

Displays internal data sampling values and bit data on/off, allowing you to know the fault circumstances.

•M11: Save of parameter settings, load, and comparison Inverter parameter settings can be saved in batch form into

nonvolatile memory using the touch panel.

They are retained when the power is turned off.

The saved data can also be loaded to the inverter.

Current inverter settings and values saved on the touch panel can be compared with each other.

Inverter application and dimensions

VM5/FM5

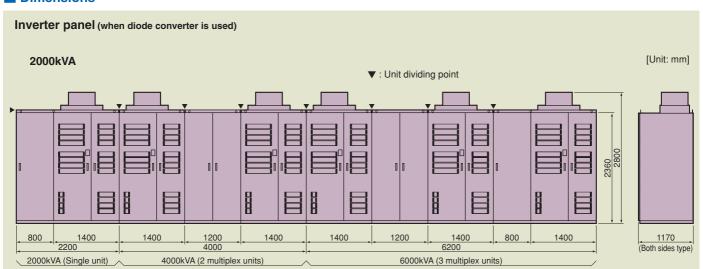
Basic inverter capacity and bank units

| Capacity [kVA] | 1200 | 2000 | 2400 | 4000 | 3600 | 6000 |
|---------------------------------|-----------------|------|-------------|--------|-------|--------|
| Composition (unit quantity) (*) |) 1 2 multiplex | | 3 multiplex | | | |
| Current [A] | 866 | 1443 | 866×2 | 1443×2 | 866×3 | 1443×3 |
| Overload capability | 150% for 1min | | | | | |
| Approx. mass [kg] | 1600 | 2300 | 2600 | 4400 | 3600 | 6700 |

^{(*):} Available maximum unit is 8 multiplex.

Note: Single unit only is applied, if FM5 (V/f control) is selected.

Dimensions

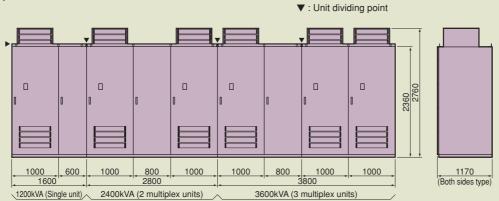


Note: Planned dimensions are indicated for 4,000kVA (2 multiplex units) and 6,000kVA (3 multiplex units). They are subject to change without prior notice.

Inverter panel: Self-standing, enclosed type

Finish color: JEM standard Munsell 5Y7/1 (semi-gloss) for internal and external

1200kVA



Inverter panel: Self-standing, enclosed type

Finish color: JEM standard Munsell 5Y7/1 (semi-gloss) for internal and external

Converter specifications and dimensions

VM5/FM5

- When regeneration function is generally unnecessary: Diode converter
- When the regenerative side capacity is smaller than that on the drive side:
 Combination of diode converter and PWM regenerative converter
- When regenerative capacity equivalent to that on the drive side is necessary:
 PWM converter (thyristor converter also available)

Specifications, dimensions and masses

Diode converter

| Rated output | Output | Input | | | Output | | Dimensions | Approx. | | |
|--|----------------|-------------|------------------|----------------------|----------------------------|-------------------|----------------|--------------|--|--|
| capacity (*1) [kW] (at 1200V DC output) | current [A] | Frequency | Voltage | Control power supply | Voltage | Overload capacity | W×D×H [mm] | mass [kg] | | |
| 3300 | 2750 | 50/60Hz ±5% | , | 3-phase, 200/220V | 1200V DC ±10% | 150% for 1min | 1100×1170×2620 | 1100 | | |
| 5940 | 4950 | | 3-phase 460V±10% | -15 to +10% | (depends on input voltage) | | 2200×1170×2620 | 2200 | | |

^{(*1):} Diode converter of capacity over 5,940kW can also be produced. Please contact us for details.

PWM converter

| Rated output capacity | Output | Input | | Output | | Dimensions (*2) | Approx. | |
|-----------------------|----------------|-------------|---------------|----------------------|----------|-------------------|----------------|--------------|
| [kW] | current [A] | Frequency | Voltage | Control power supply | Voltage | Overload capacity | | mass [kg] |
| 920 (unit capacity) | 866 | 50/60Hz ±5% | 3-phase, 720V | 3-phase, 200/220V | 1250V DC | 150% for 1min | 1600×1170×2760 | 1600 |
| 920×2 (2 multiplex) | 866×2 | | ±10% | -15 to +10% | | | 2800×1170×2760 | 2600 |
| 920×3 (3 multiplex) | 866×3 | | | | | | 4600×1170×2760 | 4200 |
| 1530 (unit capacity) | 1443 | | | | | | 2200×1170×2800 | 2300 |
| 1530×2 (2 multiplex) | 1443×2 | | | | | | 4000×1170×2800 | 4400 |
| 1530×3 (3 multiplex) | 1443×3 | | | | | | 6200×1170×2800 | 6700 |

^{(*2):} Dimensions of PWM converter panels are same as those of inverter panels shown on P7.

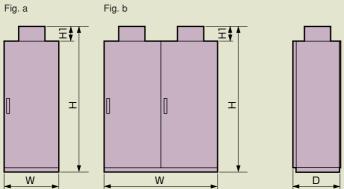
PWM regenerative converter

| Peak regenerative amount [kW] | Regenerative voltage | Dimensions (*3) W×D×H [mm] | Approx. mass [kg] |
|-------------------------------|----------------------|----------------------------|-------------------|
| 1200 (unit capacity) | 3-phase, 460V | 1600×1170×2760 | 1600 |
| 1200×2 (2 multiplex) | | 3600×1170×2760 | 3200 |

^{(*3):} Dimensions of PWM regenerative converter panels are same as those of inverter panels shown on P7. The width of a 2 multiplex panel, however, is larger by 800mm than that of an inverter panel.

Dimensions

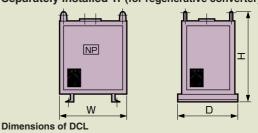
Diode converter panel



Diode converter panel: Self-standing, enclosed type Finish color: Munsell 5Y7/1 for internal and external

| Diode DC power | Dimensio | ns [mm] | Fig. | Approx. | | |
|----------------|----------|---------|------|---------|---|------|
| supply current | | | | mass | | |
| rank [A] | W | D | Н | H1 | | [kg] |
| 2750 | 1100 | 1170 | 2630 | 270 | а | 1100 |
| 4950 | 2200 | | | | b | 2200 |

Separately installed DCL (for diode converter)
Separately installed ACL (for PWM converter)
Separately installed Tr (for regenerative converter)



Diode DC power Dimensions [mm] Approx. supply current mass [kg] W rank [A] D Н 2750 800 720 1050 500 4400 1000 900 1400 950

Note: 2 units of DCL are required per converter, as DCL's are good for 3 levels.

Dimensions of ACL

| ACL | Dimension | Approx. | | | |
|-------------|-----------|---------|------|---------|----|
| | W | D | Н | mass [k | (g |
| Single unit | 1200 | 900 | 1600 | 1100 | |

Note: An ACL is good for a unit PWM converter.

Dimensions of Tr

| Tr | Dimensio | Approx. | | |
|-------------|----------|---------|------|-----------|
| | W | D | Н | mass [kg] |
| Single unit | 1150 | 1000 | 1600 | 1560 |

Note: A Tr is good for a unit regenerative converter.

The width of 920kW×3 (3 multiplex) panel only, however, is larger by 800mm than that of an inverter panel.

Maintenance tool (option)

VM5/FM5

■ PC loader (FLOAD for Windows)

Although maintenance and adjustment can be performed from the touch panel mounted on the panel face, an optional PC loader is available as a maintenance/adjustment tool. The PC loader installed in a notebook PC, has better operability and visibility than the touch panel. The trace-back data is useful for locating any fault trip.

Main functions of FLOAD for Windows

●Trace-back data

Upon fault occurrence, the cause as well as the waveform data and bit on/off statuses of the speed, current and other major items are registered. You can proceed to analysis of error circumstances, quick action and recovery. Details of up to 2 of the latest error occurrences can be retained.

•Control parameter setting, change, display and storage Control parameter settings can be saved with arbitrary filenames and comments and changed on a PC. Thus, the inverter control parameters can be controlled on a PC.

Running status display

Current inverter running statuses can be viewed at a glance thanks to the block diagram, actual value and internal data indications.

• Fault cause display

Up to 2 faults with up to 20 causes each are indicated together with the time and date of occurrence.

●Test run operation

The loader facilitates easy start and stop of the inverter while its statuses are displayed on the "running status indication screen".

•Multi-window display

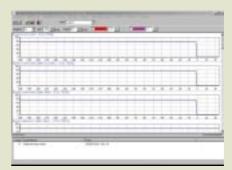
Several window indications can be displayed on a single screen, thereby allowing you to simultaneously monitor multiple information sources.

■ External AO card (type: RGGW1AAU-0070D)

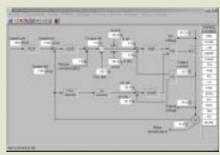
Inverter internal data (signal selection out of about 60 data) can be outputted by 4 channels in $\pm 10 \text{V}$ of analog voltage. They are isolated from the inverter.

Special lifter

The inverter can be replaced by a small number of persons. The inverter, as well as the converter, can be handled upon changing the load bucket.



Trace-back data (inverter waveform at fault) window



Running status window



Multi-window display

■ plusFSITE (*1) (Field Web adapter)

This adapter enables users to carry out remote monitoring of inverters promptly and easily with their own personal computers without using a dedicated system.

Main features

Web server function

Inverters can be monitored from the browser of a personal computer. (Display screen can be changed if requested.)

Mail sending function

Actions can be reported periodically from inverters. Upon fault occurrence, mail, including trace-back data, is transmitted.

● Applicable to the FRENIC4400VM5/FM5 and other Fuji Electric products.

(*1): plusFSITE: Fuji Supervising Interface Terminal for various Equipment



f(s)NISDAS (*2)

The inverter monitoring can be centralized at high speed.

Main features

Real time monitoring

Inverter data can be sampled every 10ms (for up to 32 inverters simultaneously).

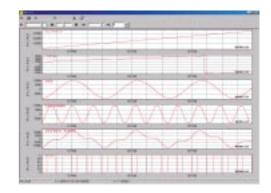
Trace-back data acquisition

Trace-back data stored in the inverter can be acquired.

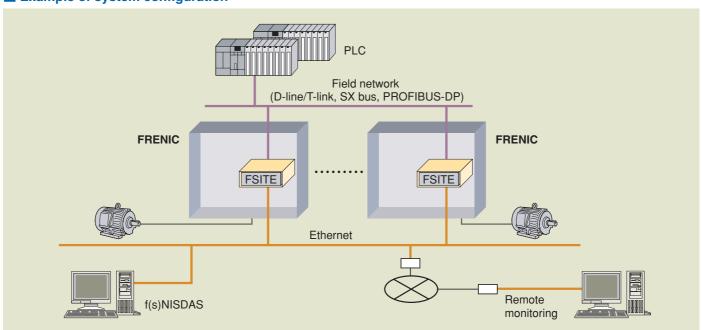
PLC internal data acquisition

Fuji general-purpose PLC (MICREX-SX) internal data can be acquired.

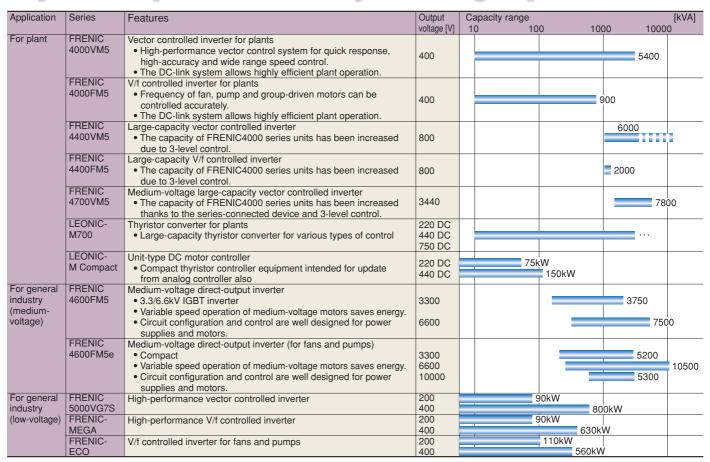
(*2): f(s)NISDAS: Using open-Network & I.T., based on SX, Diagnosis and Analysis System



■ Example of system configuration



Adjustable speed drives of Fuji Electric group



Ordering information

When placing an order or making an inquiry, please state the following.

| Application | on of inverter | | | | | |
|--|-------------------|-------------------|---------------------------------|-----------------------|--------------|----------------------------|
| | | | | | | |
| Load mad | chine specificat | tions | | | | |
| Name: □Pump □Fan | | □Fan □Bl | Blower □Air compressor □Other (| |) | |
| Load torqu | ue characteristic | s: Square-law spe | ed | ☐Constant torque ☐Con | | ☐Constant output |
| Moment of load inertia after conversion into motor shaft (J): kg · n | | | | | | kg·m² |
| Overload: | | % | | | | |
| Input spe | cifications | | | | | |
| Rated voltage: | | V± | % | Rated frequency: | Hz ± | % |
| Control power source: | | -phase, | -wire | e, V, | Hz | |
| Driven me | otor | | | | | |
| Motor specifications: □Squirrel-cage rotor □ (| | | |) , | ☐Existing | \square New installation |
| Rating | Output: | kW | No. of poles | : | Voltage: | kV |
| | Frequency: | Hz | Speed: | r/min | Current: | Α |
| Speed co | ntrol | | | | | |
| Control range: r/mi | | r/min to | 1 | r/min | | |
| Rotationa | al/frequency se | tting method | | | | |
| | | | | | | |
| Ambient (| conditions | | | | | |
| Installation | n location: Indoc | or Humidity: | %RH | Temperature: | °C Altitude: | m |
| Provision of air conditioning: | | | | Limit on carrying-in: | | |

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